

## **GPA-25 Palletizing Robot**

with exchange coupler for vacuum and fork gripper

6-axis-robot for dynamic palletizing and depalletizing on up to 2 pallets





other packages,

optionally with slip sheet or cardboard magazine

**System** 6-axis-robot

Vacuum gripper Fork gripper **Product width** 100 - 400 mm,

optionally also bigger

100 – 600 mm **Product length Product height** 

50 - 400 mm

other heights upon request

Load capacity max. 19 kg\*

approx. 1800 mm, incl. pallet\* Pallet height max.

**Empty pallet height** 130 mm (min.) – 150 mm (max.)

Speed max. 11 cycles/min.\* 150 - 260 mm

150 - 380 mm, back length

35 - 230 mm

11 kg\*

approx. 1600 mm, incl. pallet \* 140 mm (min.) – 160 mm (max.)

6 cycles/min.\*

**Pallet formats** 800 x 1200 mm, 1000 x 1200 mm, 40 x 48", 1165 x 1165 mm, 45 x 45"

(other pallet formats possible)

**Mechanical construction** compact aluminum screw construction, steel welded construction

**Drive** 6 controlled Servo axes Voltage 3 x 380 - 480 VAC, 50/60 Hz

Power consumption approx. 3 kVA

**Fuse** 3 x 16 A, slow-blow fuse+

Special NAS versions for North America conform to the ANSI standard.

The UL standard is not met.

Air pressure min. 6 bar

Air consumption depending on gripping device

Control IPC with RobAdmin palletizing program as a configuration interface for

setting the package and pallet sizes and the layer patterns

Color scheme as shown (see above).

<sup>\*</sup>The data given is interdependent with product dimensions, pallet format, pallet height, speed, gripping tool, column height and number of slip sheets.

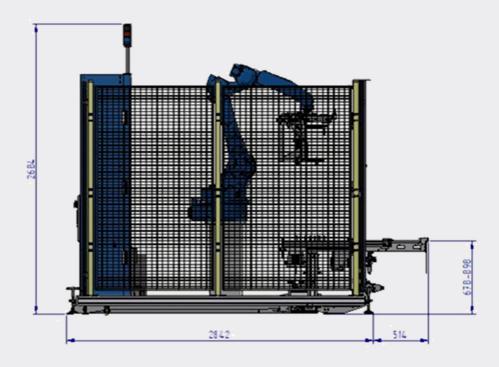


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width=3805 by 1000x1200 pallet width=3405 by 800x1200 pallet

512

3331



## Transport dimensions 3331

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